Moisture and dynamical interactions maintaining decoupled Arctic mixed-phase stratocumulus in the presence of a humidity inversion

A. Solomon$^{1,2}$, M. D. Shupe$^{1,2}$, P. O. G. Persson$^{1,2}$, and H. Morrison$^3$

$^1$CIRES, University of Colorado, Boulder, Colorado, USA
$^2$Earth System Research Laboratory/NOAA, Boulder Colorado, USA
$^3$MMM/NESL/NCAR, Boulder, Colorado, USA

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Abstract. Observations suggest that processes maintaining subtropical and Arctic stratocumulus differ, due to the different environments in which they occur. For example, specific humidity inversions (specific humidity increasing with height) are frequently observed to occur near cloud top coincident with temperature inversions in the Arctic, while they do not occur in the subtropics. In this study we use nested LES simulations of decoupled Arctic Mixed-Phase Stratocumulus (AMPS) clouds observed during the DOE Atmospheric Radiation Measurement Program’s Indirect and SemiDirect Aerosol Campaign (ISDAC) to analyze budgets of water components, potential temperature, and turbulent kinetic energy. These analyses quantify the processes that maintain decoupled AMPS, including the role of humidity inversions. Key structural features include a shallow upper entrainment zone at cloud top that is located within the temperature and humidity inversions, a mixed layer driven by cloud-top cooling that extends from the base of the upper entrainment zone to below cloud base, and a lower entrainment zone at the base of the mixed layer. The surface layer below the lower entrainment zone is decoupled from the cloud mixed-layer system. Budget results show that cloud liquid water is maintained in the upper entrainment zone near cloud top (within a temperature and humidity inversion) due to a down gradient transport of water vapor by turbulent fluxes into the cloud layer from above and direct condensation forced by radiative cooling. Liquid water is generated in the updraft portions of the mixed-layer eddies below cloud top by buoyant destabilization. These processes cause at least 20% of the cloud liquid water to extend into the inversion. The redistribution of water vapor from the top of the humidity inversion to its base maintains the cloud layer, while the mixed layer-entrainment zone system is continually losing total water. In this decoupled system, the humidity inversion is the only source of water vapor for the cloud system, since water vapor from the surface layer is not efficiently transported into the mixed layer. Sedimentation of ice is the dominant sink of moisture from the mixed layer.

1 Introduction

Arctic mixed-phase stratocumulus (AMPS) are observed to occur approximately 45% of the time on the North Slope of Alaska, with a significant increase in occurrence during spring and fall transition seasons (Shupe, 2011). Due to the presence of liquid water in these clouds, they play an important role in determining the structure of the Arctic atmospheric boundary layer (ABL) and magnitudes of surface energy budget terms. For example, Morrison and Pinto (2006) demonstrated that, in mesoscale simulations of a springtime Surface Heat Budget of the Arctic Ocean (SHEBA) case study in the Beaufort Sea area, it is necessary to adequately simulate AMPS to produce well-mixed ABLs. In addition, since cloud liquid water causes an increase in downwelling longwave radiation and a decrease in incoming shortwave radiation, inadequate simulations of Arctic clouds cause significant errors in the modeled surface energy budget (e.g., Curry et al., 2000; Solomon et al., 2009).

AMPs are typically observed to persist for days in both spring, when the Arctic Ocean is essentially ice covered, and fall, when the open ocean produces relatively large fluxes of heat and moisture into the atmospheric boundary layer (see Shupe et al., 2006; Shupe, 2011). The persistence of AMPS under both strong and weak surface forcing conditions suggests that other mechanisms also contribute to the
maintenance of these clouds, and that the relative contributions by these mechanisms may differ from spring to fall. This idea is supported by mesoscale model simulations of AMPS observed during the fall Mixed-Phase Arctic Cloud Experiment (MPACE, Morrison et al., 2008), where liquid water paths (LWPs) in AMPS during periods of open water were found to be less sensitive to changes in cloud condensation nuclei (CCN) than for clouds in modeling studies over sea ice (e.g., Pinto, 1998; Harrington et al., 1999; Jiang et al., 2001). In addition, Morrison et al. (2008) found that changes in LWP did not significantly impact large-scale circulation, in contrast to modeling studies of ice-covered conditions during SHEBA (Morrison and Pinto, 2006). However, AMPS forcing mechanisms involving cloud-top processes are likely relatively insensitive to seasonal differences of surface characteristics. In cases with and without open water, Pinto (1998) observed entrainment near cloud top by turbulent mixing (hereafter referred to as the upper entrainment zone), and downdrafts in the boundary layer that were forced by cloud top radiative cooling.

AMPS have not been studied as extensively as stratocumuli that occur in regions of the descending branch of the Hadley circulation over relatively cool subtropical oceans (Sc) (e.g., Norris, 1998). Observations indicate that the processes that maintain subtropical and Arctic stratocumulus differ due to the different environments in which they occur. For example, specific humidity inversions (specific humidity increasing with height) are frequently observed to occur coincident with temperature inversions in the Arctic (e.g., Curry et al., 1996; Tjernström et al., 2004; Sedlar and Tjernström, 2009). In a recent study, Sedlar et al. (2011) surveyed data from SHEBA, the Arctic Summer Cloud Ocean Study (ASCOS) in the central Arctic Basin, and at Barrow, Alaska, to find that specific humidity inversions occurred 75–80% of the time when low-level clouds were present. In addition, this study found a significant relationship between the existence of specific humidity inversions and AMPS that extended into the temperature inversion, highlighting the difference between AMPS and subtropical stratocumulus where the entrainment of dry air aloft prevents cloud liquid water from forming in the temperature inversion. Other important ways in which AMPS differ from warm SC include more effective cloud top radiative cooling because of the cold, dry overlying Arctic free troposphere, and vapor diffusion onto ice (Bergeron process), which acts as a potential large sink of water vapor even when there is limited liquid water. In contrast, in warm Sc drizzle grows by collision-coalescence of droplets, so as liquid water decreases, drizzle production shuts off (see Morrison et al. (2011) for a detailed discussion of this point).

To highlight differences between Arctic and subtropical stratocumulus, we first plot fields from a sounding taken during the springtime over Graciosa Island in the Azores of a single layer stratocumulus deck (Fig. 1). This subtropical sounding indicates an inversion of 6 K at 1.6–1.8 km. A decrease in specific humidity with height causes equivalent potential temperature (θe) to also decrease with height, most significantly within the inversion above cloud top. A sharp decrease in humidity causes the inversion to be potentially unstable by the Cloud Top Entrainment Instability (CTEI) criteria (e.g., Randall, 1980; Deardorff, 1980). Longwave cooling at cloud top causes the sharp, strong inversion, capping the cloud layer, and limits entrainment of warm, dry air from above (e.g., Nichols, 1984). The weak inversion at 1 km indicates that the cloud layer is decoupled from the surface. In addition, horizontal winds indicate wind shear near cloud top and divergence that is approximately constant with height within the mixed layer that balances large-scale subsidence above cloud top (not shown). These conditions are typical of marine stratocumulus-topped boundary layers. For example, see composites in Albrecht et al. (1995) and Norris (1998).

There have been many studies of decoupling in subtropical Sc. The decoupling of warm moist surface air from the cloud layer in a subtropical sounding is due to cloud layer warming by solar absorption, which limits the extent of turbulent mixing within the cloud layer generated by longwave cooling at cloud top (e.g., Nichols, 1984). However, decoupling also occurs by evaporation of drizzle below the cloud (e.g., Brost et al., 1982) and advection of the Sc cloud deck over warmer SSTs (e.g., Wyant et al., 1997). Decoupling in subtropical Sc
Fig. 2. Sounding of mid-day decoupled stratocumulus at Barrow, Alaska. (A) Measured 17:34 Z 8 April 2008 at (71.33°N,156.61°W). (B) 50 m LES simulation 20 Z 8 April 2008 at (71.33°N,156.91°W; red star in Fig. 6). Gray shading marks the extent of the cloud layer.

can cause a cloud to evaporate unless cumulus clouds form below the subcloud mixed layer and transport moisture upward to the cloud layer (Nicholls, 1984). Idealized model studies have been used to examine the impact of precipitation on these clouds. Sedimentation causes a decrease in cloud water in the upper entrainment zone, decreasing longwave cooling and turbulent mixing of dry warm air aloft into the cloud layer, ultimately increasing the liquid water path (e.g., Ackerman et al., 2004; Bretherton et al., 2007). Drizzle stabilizes the boundary layer by latent heating in the cloud layer and evaporation below cloud base, potentially depleting the boundary layer of water if drizzle is strong enough to reach the surface (e.g., Stevens et al., 1998).

In contrast to the warm Sc, a sounding containing a single-layer Arctic mixed-phase stratocumulus is plotted in Fig. 2a. This sounding was taken in spring when the Arctic Ocean was essentially ice-covered. However, satellite images show regions of open water providing a possible source of low-level moisture. A detailed discussion of this Arctic case study is provided in Sect. 2. The sounding indicates a surface temperature of \(\sim -8\) °C and surface specific humidity of \(\sim 1.7 \text{ g kg}^{-1}\). The \(\theta_e\) profile monotonically increases with height up to 500 m where the slope changes, indicating a decoupling between a stable surface layer and a cloud-driven mixed layer (the layer between 0.5–1.1 km, which contains most of the cloud layer and extends 400 m below the cloud). A temperature inversion of 4 K at 1.1 km makes the cloud top stable relative to the overlying atmosphere and defines the lower boundary of an upper entrainment zone that is approximately 50 m in depth. We have estimated the boundaries of entrainment zones by changes in the \(\theta_e\) slope, which yields similar results to assuming the top of the entrainment zone is located at the top of a region of negative buoyancy (see Deardorff (1979) for a discussion on this point). Specific humidity decreases with height from the surface to the base of the temperature inversion, where there is a coincident humidity inversion that suggests horizontal advection of warm, moist air aloft. Specific humidity at the top of the inversion is nearly equal to its value at the surface. Horizontal winds indicate significant shear at the inversion (similar to subtropical Sc, the base of the mixed layer, and near the surface. Winds are relatively weak and uniform within the mixed layer.

In this study we examine many details of AMPS using results from nested LES simulations during the DOE Atmospheric Radiation Measurement (ARM) Program’s Indirect and SemiDirect Aerosol Campaign (ISDAC, McFarquhar et al., 2011). We specifically focus on structures and processes that distinguish AMPS from subtropical Sc, such as the role that a cloud top humidity inversion plays in cloud maintenance.

In Sect. 2 we outline observations of the environmental conditions and cloud properties during ISDAC. In Sect. 3 we describe the model and experiment design. Model results are compared with retrievals and soundings taken at Barrow, Alaska, in Sect. 4. In Sect. 5 we present budgets of cloud water \((q_c)\), cloud ice \((q_i)\), water vapor \((q_v)\), total water \((q_t)\), potential temperature \((\theta)\), and turbulent kinetic energy (TKE) to quantify the processes that maintain the AMPS. Finally, we discuss our findings relative to previous studies of Arctic and subtropical stratocumulus clouds in Sect. 6.

2 Observations

2.1 Synoptic-scale features

In April 2008, ISDAC was conducted to measure mixed-phase clouds in both clean and polluted environments over the North Slope of Alaska and adjacent Arctic Ocean (see McFarquhar et al., 2011). Two “golden days” were identified where persistent, single-layer mixed-phase stratocumulus were extensively observed by aircraft and ground-based sensors. This study focuses on the 8 April 2008 case. During this time, the Beaufort Sea was generally ice covered and roll clouds were not observed, in contrast to fall conditions in the area (for example, see MPACE case study of Solomon et al., 2009). However, visible images taken on 8 April by the Terra satellite indicate that significant areas of open water east of Barrow may have impacted cloud
Fig. 3. Observationally retrieved one-hour running mean cloud liquid (A) and ice (B) water content, in g m\(^{-3}\), at Barrow, Alaska from 08–24Z 8 April 2008 (color). Hourly output of liquid water (C) and ice (D) from WRF 1 km nest. Temperature isopleths (°C) are interpolated from soundings at 4:22Z 8 April 2008, 17:34Z 8 April 2008, 05:32Z 9 April 2008. Note −13°C and −15°C contours are red to highlight inversions. Black dashed lines in (A) and (C) indicate the validation period. The gray dashed line in (A) indicates the time of the sounding.

formation and boundary layer structure during this period. Two soundings were made at Barrow on the 8th at 4:22Z and 17:34Z. The first sounding shows that the initial wind direction was northerly at the surface, gradually veering to easterly at 1.4 km and thereby indicating warm air advection. By the second sounding (see Fig. 2a), occurring after a marked surface wind shift at 08:00 UTC, winds were east-southeasterly throughout the lowest 2.0 km indicating no thermal advection as a northward-moving high pressure system was located NE of Barrow (McFarquhar et al., 2011).

2.2 Cloud and boundary layer properties

At Barrow, measurements taken with a ground-based vertically pointing 35-GHz cloud radar, a micropulse cloud lidar, and a dual-channel microwave radiometer were combined (Shupe, 2007) to reveal multi-layered mixed-phase and ice clouds extending from the surface to 3 km that persisted from 0Z–8Z until a warm frontal passage when the cloud top descended to 1 km (Fig. 3b). At 17:34Z, the temperature profile shows a sharp (~4 K) inversion at ~1 km (Figs. 2a, 3a), with
cloud top extending up into the inversion by approximately 100 m (Fig. 3a). The AMPS persisted until 12 Z 9 April with cloud top slowly descending from 1 km to 500 m over this period. The large scale forcing for our model simulation (that is applied at the lateral boundaries of the 25 km nest) has a time delay of approximately two hours relative to observations. Therefore, the cloud that was observed to start descending at 18 Z at Barrow begins to descend in the model simulation at 20 Z. Ice precipitated from the base of the AMPS, but only trace precipitation was observed at the surface by the US Climate Reference Network gauge near Barrow. Indications of a lower secondary cloud layer were observed at 10, 12, and 16 Z. The sounding at 17:34 Z (Fig. 2a) indicates that the surface and primary cloud layer were decoupled, with a well-mixed layer within and below the cloud (static stabilities close to neutral, $\frac{\partial \theta_e}{\partial z} \approx g_0$) and a stable layer below (static stabilities greater than 2K/km below 500 m). Water vapor mixing ratios decreased from 1.7 g kg$^{-1}$ at the surface to 1.2 g kg$^{-1}$ at cloud top, above which a secondary maximum of 1.6 g kg$^{-1}$ was observed.

Microphysical properties for these clouds were also derived from ground-based remote sensors. First, a cloud phase classification (Shupe, 2007) was used to determine the vertical distribution of cloud phase. Cloud ice water content (Fig. 3b), and its vertical integral the ice water path (IWP), were derived from cloud radar reflectivity measurements with an uncertainty of up to a factor of two (Shupe et al., 2006). Cloud liquid water path (LWP) was derived from dual-channel microwave radiometer measurements with an uncertainty of 20–30 g m$^{-2}$ (Turner et al., 2007), while the cloud water (Fig. 3a) was distributed vertically with a scaled, adiabatic calculation using observed cloud boundaries and interpolated radiosonde measurements. Finally, in-cloud vertical air velocity ($w$) was derived from cloud radar Doppler spectra (Shupe et al., 2008a). Between 12–24 Z, IWP exceeded LWP and liquid fraction (LF, ratio of LWP to LWP + IWP) was generally below 0.4. IWP generally exceeded 60 g m$^{-2}$ and LWP ranged between 20–100 g m$^{-2}$. IWP and LWP were significantly correlated over 2 min to 1 h averaging periods, which is meaningful because of the vertically coherent nature of the ice content shafts within the cloud mixed layer where the ice content is greatest, (Fig. 2b). Unlike AMPS observed during fall at Barrow, IWP was not depleted in downdrafts (see Shupe et al., 2008b). Cloud-averaged $w$, LWP, and IWP had maximum correlations at zero lag (results not shown).

3 Model setup and experiment design

3.1 WRF V3.1

The Weather Research Forecast (WRF) V3.1 model (Skamarock et al., 2008) is used for this study with five two-way nested grids with horizontal grid spacings of 25 km, 5 km, 1 km, 200 m, and 50 m (Fig. 4). The 50 m nest has 241 × 241 horizontal gridpoints (12 km × 12 km) and is placed just to the northwest of Barrow. The boundary layer is well resolved in the vertical by including 85 pressure levels below 800 hPa. In order to better resolve entrainment and mixing in the mixed-layer and upper entrainment zone, the vertical grid spacing ($\Delta z$) is 16 m in the cloud-driven mixed layer (0.6–1.5 km) and 8 m in the upper entrainment zone (1.2–1.4 km). Below 0.6 km and above 1.5 km $\Delta z = 50$ m. Second order diffusion with a 1.5 order TKE prediction scheme is used to parameterize subgrid turbulence in the 1 km, 200 m and 50 m nests. The model is forced with lateral and surface boundary conditions from the European Centre
Table 1. Packages used in WRF model setup.

<table>
<thead>
<tr>
<th>Package</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Radiation package</td>
<td>National Center for Atmospheric Research Community</td>
</tr>
<tr>
<td></td>
<td>Atmospheric Model longwave and shortwave radiation package.</td>
</tr>
<tr>
<td></td>
<td>The longwave code allows for interactions with resolved clouds and cloud fractions Collins et al. (2004).</td>
</tr>
<tr>
<td>Surface layer physics package</td>
<td>Monin-Obukhov with Carlson-Boland viscous sub-layer and standard similarity</td>
</tr>
<tr>
<td></td>
<td>functions following Paulson (1970) and Dyer and Hicks (1970). Surface exchange</td>
</tr>
<tr>
<td></td>
<td>coefficients for heat, moisture, and momentum computed following Webb (1970).</td>
</tr>
<tr>
<td></td>
<td>Four stability regimes are defined following Zhang and Anthes (1982).</td>
</tr>
<tr>
<td>Land surface package</td>
<td>Noah Land Surface Model; the unified NCEP/NCAR/AFWA scheme with soil</td>
</tr>
<tr>
<td></td>
<td>temperature and moisture in four layers, fractional snow cover and frozen</td>
</tr>
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<td></td>
<td>soil physics Chen and Dudhia (2001).</td>
</tr>
<tr>
<td>Planetary boundary layer mixing package</td>
<td>Yonsei University scheme (non-local-K scheme with explicit entrainment layer</td>
</tr>
<tr>
<td></td>
<td>and parabolic K profile in unstable mixed layers) in 5 and 25 km grids</td>
</tr>
<tr>
<td></td>
<td>Hong et al. (2006).</td>
</tr>
<tr>
<td>Microphysics package</td>
<td>Morrison two-moment scheme including prognostic cloud droplets, cloud</td>
</tr>
<tr>
<td></td>
<td>ice, rain, snow, and graupel/hail Morrison et al. (2009).</td>
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</table>

for Medium-Range Weather Forecasts' (ECMWF) 4X daily, T255 ERA-Interim dataset. The model is spun-up by integrating from 00:00 UTC 8 April to 12 Z UTC 8 April. The 200 m and 50 m nests are started at 18 Z and spun up by integrating for 2 h. The subsequent 90-min period 20:00–21:29 UTC 8 April is used in the analysis.

Radiation, surface layer physics, land surface, and planetary boundary layer options used in the model runs are described in Table 1. Ice is initiated by deposition nucleation, contact freezing, and immersion freezing (see Morrison and Pinto (2005) for details on parameterizations used in the model). Homogeneous freezing of cloud droplets is negligible for temperatures observed during ISDAC. The concentration of ice nuclei (IN) acting in deposition and condensation freezing modes is specified from observations using the continuous flow diffusion chamber from the MPACE campaign (Prenni et al., 2007), with a mean of 0.16 L$^{-1}$. Further discussion of the treatment of IN in deposition freezing mode is included in Sect. 5.2. Cloud droplets are activated in regions of low cloud water content using resolved and subgrid vertical motion (Morrison and Pinto, 2005) and a log-normal aerosol size distribution to derive cloud condensation nuclei spectra following Abdul-Razzak and Ghan (2000). The log-normal dry aerosol size distribution was fit to in-situ measurement from the National Research Council of Canada Convair-580 (personal communication, Peter Liu, Environment Canada, 2010) with a size distribution given by

$$\frac{dN}{d\ln r} = \frac{N_i}{\sqrt{2\pi} \ln \sigma} \exp\left\{ \frac{\ln^2(r/r_m)}{2\ln^2\sigma} \right\}$$  \hspace{1cm} (1)$$

where $N$ is the number concentration of aerosols and $r$ is the particle radius. The parameters $N_i$, $r_m$, and $\sigma$ are total number concentration, geometric mean radius and standard deviation of each particle mode, and are given the values $165$ cm$^{-3}$, $1.3$ $\mu$m, and $1.4$, respectively. Aerosol composition is assumed to be 30% insoluble by volume, with the remaining soluble component consisting of ammonium bisulphate.

The microphysical cloud scheme used in this study includes two-moments for cloud droplets, rain, ice, snow, and graupel/hail. This means a prognostic equation for mixing ratio and number concentration is integrated for each of the 5-hydrometeor classes. Morrison et al. (2009) provide details of the parameterizations used in this microphysical scheme.

3.2 Experiment design

A significant amount of open water was observed during ISDAC along the eastern Alaskan coast. However, this modeling study is focused on the maintenance of decoupled Arctic mixed-phase stratocumulus. We therefore removed all regions of open water and set the ocean surface uniformly to sea ice. However, removing the open water had a negligible impact on the simulations presented in this study.

In this model study, WRF is run with high enough resolution to resolve turbulent eddies that contain the most kinetic energy and transport the most heat and momentum, i.e. as a large eddy simulation (LES). However, different from traditional LESs, this study does not use periodic boundary conditions, where an eddy that is advected out one side of the domain enters through the other side of the domain. Rather, eddies from the 200 m nest are advected into the 50 m nest and variability with scales finer than 200 m evolve within the 50 m nest. This modeling strategy has been successfully applied to simulations of boundary layer clouds in heterogeneous conditions that are directly linked to synoptic systems (for example, see Zhu et al., 2010). In the 50 m nest, it takes approximately 1 km for the turbulent structures to spin up (results not shown).
with angled brackets) across a 6.5 km × 6.5 km square domain do- 

tom the processes involved in the maintenance and persistence of observed springtime Arctic mixed phase stratocumulus (constants used in this study are provided in Table 2).

The quasi-conserved variables used in our study are \( \bar{\theta} \) and \( \bar{q}_v \), where \( \bar{\theta} \) is equal to

\[
\bar{\theta} = \left( T + \frac{L}{c_p} q_v \right) \left( \frac{p_0}{p} \right) \left( \frac{k}{\rho} \right) + \left( \frac{L}{c_p} q_v \right) \left( \frac{p_0}{p} \right) \left( \frac{k}{\rho} \right)
\]

and the prognostic equations for \( \bar{\theta} \) and \( \bar{q}_v \) constituents are

\[
\frac{\partial \bar{\theta}}{\partial t} = \left( \frac{p_0}{p} \right) \left( \frac{k}{\rho} \right) Q_1 - \bar{u} \cdot \nabla \bar{\theta} - w \frac{\partial \bar{\theta}}{\partial z}
\]

\[
\frac{\partial \bar{q}_v}{\partial t} = Q_{2 v} - \bar{u} \cdot \nabla \bar{q}_v - w \frac{\partial \bar{q}_v}{\partial z}
\]

where \( Q_1 \) is diabatic heating, composed of radiative heating \( (Q_r) \) and condensational heating \( (Q_c) \), and \( Q_{2 v} \) is diabatic moistening due to phase changes. Sedimentation, or gravitational settling, is included in the \( Q_{2 v} \) term in Eq. (4). \( q_s \) can be vapor \( (q_v) \), liquid \( (q_c) \), ice + snow + graupel \( (q_i) \), or total water \( (q_t = q_v + q_c + q_i) \).

To separate mesoscale and turbulent variability, all turbulent fluxes are calculated with 15 min averaged fields. Fifteen minutes is approximately the time scale between mesoscale variability and the “energy-containing” scales in the retrieved vertical velocity spectra (results not shown). For example, for vertical fluxes, the turbulent vertical flux is \( \bar{w} \bar{q}_v = \bar{w} \bar{q}_v - \bar{w} \bar{q}_v \), where primes denote deviations from the temporal averages and overbars signify temporal averages over 15 min (equal to the average over 1800 time steps). Vertical profiles are calculated horizontally averaging (denoted with angled brackets) across a 6.5 km × 6.5 km square domain, 1 km away from horizontal boundaries. The budgets expressed in Eqs. (3–4) are also averaged over updrafts and downdrafts separately to investigate the turbulent dynamics that maintain the mixed layer and cloud layer structures.

In a nearly horizontally homogenous system (where the length scale of the most energetic turbulent eddies is much smaller than the characteristic scale of the eddy correlations) the TKE-budget can be written as (see Garratt, 1992, pg. 33, eqn 2.74a):

\[
\bar{\omega}^2 = \frac{g}{\theta_0} \left( \frac{\bar{w} \bar{q}_v}{\bar{w} \bar{q}_v} - \left( \bar{u}' \bar{w}' \frac{\partial \bar{\theta}}{\partial z} + \bar{v}' \bar{w}' \frac{\partial \bar{\theta}}{\partial z} \right) - \frac{\partial \bar{w}^2 e}{\partial z} - \frac{\partial \bar{w}^2 p^i}{\partial z} - \bar{e} \right),
\]

where \( e = 0.5 (u' u' + v' v' + w' w') \),

\[
\bar{\theta}_v = \theta (1 + 0.61 q_v - q_i - q_c),
\]

and buoyancy flux \( = \bar{w} \bar{\theta}'_v \)

The term \( E \) is storage, \( B \) is buoyancy production, \( S \) is shear production, \( T \) is turbulent vertical transport, \( P \) is pressure transport, and \( D \) is viscous dissipation.

4 Validation of 1 km nest at Barrow

The model simulates the vertical extent and ice water content (IWC) of the predominantly ice cloud that was observed between 0–8 Z (results not shown). The model also simulates the mixed phase stratocumulus that was observed starting at 8 Z, with maximum liquid water content (LWC) at 1.3 km, and the slow descent of the cloud from 8 Z 8 April to 12 Z 9 April (compare Fig. 3a, b, c, d). At times, multiple layers of liquid are produced within the model, consistent with ground-based observations. Modeled IWC in the AMPS is underestimated by a factor of 3–4, a difference that is somewhat larger than the expected uncertainty in retrieved IWC. However, qualitatively, the model does tend to show a relative increase in IWC in a layer near the surface, which is consistent with the radar-derived IWC profiles. The 1 km, 200 m, and 50 m nests produce AMPS with equivalent structure and magnitude (figure not shown). Cold temperatures aloft (estimated from the soundings) descend more slowly in the simulation causing a single-layer AMPS to form at 1.2 km from 18–22 Z, while observations show cloud tops closer to 800 m at this time. However, this difference in inversion base height between the model and sounding does not change the qualitative, mean state characteristics, i.e. both have cloud layers that are decoupled from the surface layer.

In Fig. 5 we compare \( w \), LWP, and IWP power spectra at Barrow for the 2-h period 20–22 Z from retrievals, the 1 km nest and 50 m nest (50 m nest values are taken to the west of Barrow at 71.33°N, 156.91°W; red star in Fig. 6). The \( w \) time series used in this analysis are vertical averages over the layer containing cloud liquid water, as vertical velocity structures were typically vertically coherent in nature. Looking at the \( w \) spectra first, the 50 m nest is reproducing the variability well into the inertial subrange \( (v > \sim 0.01 \text{ s}^{-1}) \), while the 1 km nest can only resolve time scales longer than \( \sim 10 \text{ min} (v < \sim 2 \times 10^{-3} \text{ s}^{-1}) \), which is consistent with the 7 m s

1 horizontal wind speed and a 4Δx resolution. It is interesting to note that the 1 km nest can simulate similar coarse-scale variability and structure as the 50 m nest despite not resolving small scales. Similar results are seen for the
Fig. 5. IWP (top), LWP (middle), and \( w \) (bottom) spectra at Barrow for the 2 h period 20–22 Z 8 April 2008 from retrievals (black), 1 km nest (blue) and 50 m nest (red), in units of \( g^2 m^{-4} \), \( g^2 m^{-4} \), and \( cm^2 s^{-2} \), respectively. The spectra for the 50 m nest are obtained 0.30 degrees (\( \sim7 \) km) west of Barrow, marked by the red star in Fig. 6.

LWP; both the 50 m and 1 km nests have similar variability on 10–20 min time scales while only the 50 m resolves the finer scale variability. IWP spectra show that the 50 m nest is underestimating variability on small scales, even though these scales are better simulated in the LWP and \( w \) spectra, suggesting difficulties with initiation and/or growth of cloud ice and snow in the model.

Fig. 6. Liquid water path (color) and winds (flags) at maximum liquid water level at 20 Z on 8 April 2008 for the 50 m nest. A half barb on the wind flags indicates 5 m s\(^{-1}\) and a full barb 10 m s\(^{-1}\). The square marks the region used to make total, downdraft, and updraft averages (130 \( \times \) 130 grid points). The red star marks the location of vertical profiles plotted in Fig. 2 and the 50 m spectra in Fig. 5. The red dashed line marks the diagonal slice plotted in Fig. 7. Barrow, Alaska is located directly to the east of the red star, to the right of thin black lines in the lower right marking the Alaska coastline.

5 Nested LES simulations

5.1 Comparison with a sounding at Barrow

In this study we focus our analysis on the single layer AMPS that persisted from 18–22 Z in the model. In Fig. 2, we compare the environmental conditions to the west of Barrow at 20 Z in the 50 m nest (hereafter referred to as the LES) to the nearest-in-time sounding taken at Barrow at 17:34 Z. Note that these vertical profiles are for different times at different locations since the modeled cloud structure evolves slightly later than observed, and this study focuses on the region to the west of Barrow with uniform surface conditions. The red star in Fig. 6 shows the location of vertical profiles plotted in Fig. 2b. The LES simulates a well-mixed surface layer up to \( \sim400 \) m and a second mixed layer associated with the cloud (referred to hereafter as the cloudy mixed layer or simply mixed layer) as in the sounding; however, the intervening stable layer is somewhat deeper and offset vertically in the LES relative to the observations. The simulated cloud-top temperature inversion strength of 5 K is slightly greater than the observed 4 K inversion; however, the...
simulated humidity inversion of 0.4 g kg\(^{-1}\) is slightly weaker than observed. Cloud water extends into the temperature inversion by approximately 50 m in both the LES and sounding. On average, the cloud water maximum is at the humidity inversion base and 23% of simulated cloud liquid water is located within the inversion. Unfortunately, this vertical structure cannot be validated since the remote-sensor observations do not contain sufficient information on the vertical distribution of liquid water in mixed-phase clouds. Observed winds indicate shear in the surface layer and weaker winds within the cloudy mixed layer. While qualitatively similar in many regards, the LES shows larger shear at cloud top; part of this difference may be due to vertical smoothing of the radiosonde measurements during data acquisition.

5.2 Comparison with aircraft measurements

A research flight was conducted on 8 April with the National Research Council of Canada Convair-580 (McFarquhar et al., 2011). Between 22:27 and 23:00 UTC a series of ramped ascents and descents through the cloud layer were executed between Barrow and 71.8° N, 160° W. Comparisons are made for this space and time between measured (see Avramov et al., 2011, Fig. 10) and modeled (see Supplement Fig. 1) vertical profiles of horizontally averaged droplet number concentrations (NC), LWC, ice number concentration (NI) for sizes larger than 100 microns, and IWC. The modeled NC is essentially determined by the aerosol concentration specified in the model and is within the range of observed values. Modeled LWC is at the high end of the observational estimate and mean values are 50% larger than measured mean values. Modeled NI is ~0.751 from the base of the cloud to 0.5 km, which is larger than the observational estimate but within a factor of two of the mean. Our mean peak IWC values of ~0.018 g m\(^{-3}\) above 500 m are lower than the baseline IWC observational estimates; however, as discussed by Avramov et al. (2011), IWC calculations from measured size distributions can vary by at least a factor of five when ice crystal habit assumptions are taken into account. With this significant observational uncertainty, the degree to which the model underestimates IWC, if at all, cannot be determined. In general, considering the observational uncertainties and the difficulty in comparing data sets with differing spatial and temporal sampling, these comparisons indicate that the LES results are not inconsistent with in situ measurements.

These comparisons with aircraft observations provide further insight into the modeled ice nucleation processes. Depositional freezing is parameterized to only be active if NI drops below a fixed threshold value (Morrison et al., 2009). In our primary simulation, NI generally exceeded the specified threshold of 0.16 l\(^{-1}\), meaning that contact and immersion freezing dominated the modeled ice nucleation. In sensitivity simulations, deposition freezing only became significant when the threshold was greater than ~0.71 l\(^{-1}\), or the approximate average modeled NI. Simulations with much higher thresholds lead to glaciation of the cloud. Since the aircraft observed NI was actually slightly smaller than 0.71 l\(^{-1}\), depositional thresholds higher than this value are not justified. Therefore, the IN concentrations of about 81 l\(^{-1}\) measured during the 8 April flight (McFarquhar et al., 2011) must be representative of concentrations in the free troposphere but not those accessible to the cloud layer itself. The relative consistency between modeled and observed NI supports a low threshold value for the deposition freezing parameterization. Small concentrations of IN within the cloud layer relative to those measured above cloud top may be explained by a large sink of IN through precipitation versus a much smaller source through entrainment at cloud top (Fridlind et al., 2011).

5.3 Vertical structure along mean wind in cloud layer

The spatial distribution of LWP in the LES at 20 Z is plotted in Fig. 6. The square in the figure marks a region that is 1.0 km away from any boundary and consistently has single layer AMPS with cloud tops at ~1.29 km for the 20–22 Z period. This region is used for statistics discussed in the following sections. Figure 7 shows the vertical structure of various fields along the red dashed line in Fig. 6, which is approximately parallel to mean winds in the cloud layer. This figure depicts a single layer cloud with top at ~1.29 km, base at ~1 km, and cloud water extending into the inversion by about 50 m. The inversion base is at 1250 m. Cloud ice forms within the liquid cloud layer (Fig. 7b), sometimes very near the top, and precipitates below the cloud layer. The precipitating ice sublimates to some degree in a dry layer below the cloud, but tends to grow again in the relatively moist near-surface layer.

Characteristic subgrid vertical velocity is estimated from predicted subgrid turbulent kinetic energy, assuming isentropic turbulence, as \(w'_t = \left(\frac{2}{3} \text{TKE}^2\right)^{\frac{1}{2}}\). Subgrid vertical velocity is seen in three physically distinct regions: at the inversion top, in a layer encompassing the cloudy mixed layer, and near the surface (Fig. 7c). The magnitude of the subgrid vertical velocity in the mixed layer is ~4X smaller than the resolved vertical velocity but still significant. Resolved downdrafts are stronger and narrower than updrafts (Fig. 7d), consistent with generation by cloud-top cooling. The strongest vertical motions are generally confined to the cloud layer itself. Small-scale variability is seen within and above the inversion. Generally weak vertical motions also occur below 0.7 km.

Figure 7e, f show \(\theta_e\) and total water (\(q_t\)) along the diagonal slice. Since these two fields are quasi-conserved during diabatic changes including vapor-liquid phase changes (\(\theta_e\) is not conserved during liquid-ice phase changes), they are commonly used to identify mixed-layer structure and define idealized mixed-layer models. A mixed layer is seen in Fig. 7e, f to extend from the base of the inversion at 1250 m.
Fig. 7. Vertical structure at 20 Z along mean cloud layer wind from 50 m nest. (A) Cloud water, in units of g kg\(^{-1}\). (B) Cloud ice, in units of g kg\(^{-1}\). (C) Subgrid \(w\), in units of cm s\(^{-1}\). (D) Vertical velocity, in units of m s\(^{-1}\). (E) Equivalent potential temperature, in units of K. Red (blue) lines are contours of \(q_c = 0.12 \) (0.01) g m\(^{-3}\) to identify max (min) of the cloud layer. (F) Total water, in units of g kg\(^{-1}\). Isotherms are shown with colored contour lines in all figures except (E).
5.4 Total domain averages

5.4.1 Buoyancy fluxes

Figure 8 shows the vertical buoyancy flux, \( \frac{w'\theta'_{e}}{e} \), and \( \theta_{e} \) averaged temporally over 90 min and horizontally over the square domain in Fig. 6. Positive buoyancy flux occurs in the mixed layer from about 0.9 to 1.24 km and near the surface below 0.2 km. Weak negative buoyancy flux is present between these two layers. The cloud top is capped by a layer of negative buoyancy flux, associated with the damping effect of entraining air from the temperature inversion. This entrainment is forced by radiative cooling. The peak negative flux occurs at 1.27 km (Fig. 8b), 30 m above the top of the mixed layer. Motions in regions with positive buoyancy flux are stabilizing, producing TKE at the expense of potential energy. Motions in regions with negative buoyancy flux are destabilizing, reducing TKE to produce potential energy. Note that the cloud top actually resides in a region of negative buoyancy flux. The small difference between the buoyancy flux and potential temperature flux (\( w'\theta' \), red curves) indicates that water variations are making a negligible contribution to the buoyancy flux.

Figure 8b, c are the same curves as in Fig. 8a enlarged to show the correspondence between buoyancy flux and a \( \theta_{e} \)-based layer definition for the upper entrainment zone (8b) and the lower entrainment zone (8c). The dash-dot gray lines indicate the \( \theta_{e} \) slopes in the mixed layer and the ~dry adiabatic lapse rate above (below) the upper (lower) entrainment zones. The depth of the entrainment zones is estimated as the region where the slope of \( \theta_{e} \) deviates from the constant slopes marked with the gray dash-dot lines; specifically, 1.24–1.3 km (depth = 60 m) for the entrainment zone at cloud top and 0.62–0.82 km (depth = 200 m) for the entrainment zone at the base of the mixed layer. Therefore, the \( \theta_{e} \) profile indicates that there are effectively two mixed-layers, one being the actual boundary layer from the surface up to about 400 m and the other being the cloud-driven mixed-layer. Thus, the cloud is decoupled from the surface and does not derive much (or any) of its energy from surface forcing.

5.4.2 Potential temperature tendencies

Longwave radiative cooling dominates over condensation and advection warming tendencies within the upper entrainment zone, causing the net potential temperature tendency in this zone to be a cooling of up to \(-40 \text{ K day}^{-1}\) (Fig. 9a). The maximum cooling tendency is located somewhat higher in the entrainment zone than the longwave cooling peak due to the turbulent vertical divergence of \( \theta_{e} \) fluxes (a cooling) between 1.27–1.35 km (WTP in Fig. 9). The total advective tendency is also significant within the upper entrainment zone, where values of \(+20–40 \text{ K day}^{-1}\) occur (ADV in Fig. 9). Contributions from both horizontal and vertical flow exceed 30 K day\(^{-1}\) (results not shown), but tend to partially cancel such that the total advective tendency is smaller. The total advective term is highly variable in time, with the standard deviation of 15-min horizontally- and vertically-averaged advective tendencies being 26.6 K day\(^{-1}\) compared to only 2.9 K day\(^{-1}\) for longwave cooling. This variability is primarily due to advection by mean fields, as the ratio of standard deviations for vertical mean and eddy advective tendencies is 16/5. Contributions to \( \theta_{e} \) tendencies from solar radiation are negligible.

Longwave cooling effects extend 80 m down into the mixed-layer (130 m into the cloud), with average values near \(-80 \text{ K day}^{-1}\) at the mixed-layer top (Fig. 9a). However, the effects of this cooling are largely offset by turbulent vertical convergence of \( \theta_{e} \) flux (a warming) between 1.18–1.27 km, which is due to entrainment of sensible heat from above the temperature inversion. In this case, the surface is warmer than the cloud, causing a net longwave warming at cloud
5.4.3 Turbulent kinetic energy tendencies

TKE tendency terms are calculated following Eq. (5) and then averaged horizontally across the total square domain. The shear (S), buoyancy (B), TKE transport (T), and residual (R = P + D) terms are plotted in Fig. 10. The storage term is negligible so $B + S + T + R \approx 0$. The gray shading in Fig. 10 marks the entrainment zones. The mean resolved TKE is approximately constant $0.4-0.5 \text{ m}^2\text{s}^{-2}$ within the mixed layer, decreasing to below $0.1 \text{ m}^2\text{s}^{-2}$ above 1.32 km and below 0.7 km.

In the upper entrainment zone, negative TKE tendencies due to buoyancy effects associated with the temperature inversion, are largely balanced by TKE generation by pressure transport, as the dissipation contribution to R can only be negative. At the base of this entrainment zone, TKE is primarily produced by shear and is transported downward into the mixed layer. Within the mixed layer, TKE is produced by buoyancy effects resulting from radiative cooling above 1.15 km and evaporative cooling plus advection below 1.15 km (see Fig. 9). This buoyancy, combined with shear, produces TKE within the mixed layer, much of which is also dissipated within the mixed layer. Buoyancy contributes to negative TKE tendencies near the mixed-layer bottom; however, this term is small relative to TKE transport from mixed-layer top to bottom. All TKE tendencies approach zero just below the mixed-layer bottom, consistent with this layer being energetically decoupled from the lower troposphere and surface.

5.4.4 Averaged water tendencies and mean fields

Vapor, liquid water, and ice tendencies, as well as mean vertical velocity, $\theta_e$, vapor, and cloud water profiles averaged over the square domain in Fig. 6 and temporally averaged over the 90-min period are plotted in Fig. 11. Figure 11a shows the contribution of cloud water, cloud ice, and water vapor to the total water tendency. The entrainment zones are indicated with gray shading. Water vapor decreases throughout the upper entrainment zone, partially due to condensation, resulting in positive cloud water tendencies in this zone. Small positive ice tendencies start just below the top of the upper entrainment zone. The loss of total water in the mixed layer is relatively constant with height, resulting from loss of both cloud liquid water and water vapor above 1 km and only vapor below 1 km. Below the lower entrainment zone, vapor increases due to sublimating ice precipitation, surface moisture fluxes, and mean horizontal advection.

On average a weak subsidence of $-0.4 \pm 0.4 \text{ cm} \text{s}^{-1}$ occurs at and above cloud top (Fig. 11b). A mean subsidence of up to $-2.5 \text{ cm} \text{s}^{-1}$ occurs within the mixed layer, with large variability. Weak upward motion occurs below the mixed layer. At the top of the upper entrainment zone, mean vertical velocity goes to zero with relatively limited variability ($< \pm 0.5 \text{ cm} \text{s}^{-1}$), suggesting little movement through this
interface. Vertical velocities in individual up- and down-drafts within the mixed layer are often 100 times larger than these mean values. Twenty three percent of the vertically integrated cloud liquid water is located within the inversion (Fig. 11c). Maximum liquid water occurs at the water vapor minimum, which is at the inversion base. Significantly larger values of water vapor occur above and below the cloud layer.

Time series of 15-min averaged water content tendencies in the upper entrainment zone and mixed layer are plotted in Fig. 12. A close compensation between cloud liquid water and water vapor tendencies is seen in the upper entrainment zone and mixed layer, always resulting in a net loss of total water of between $-50$ to $-200 \text{ g m}^{-2} \text{ day}^{-1}$. The ice tendency in this zone is negligible. In the mixed layer, the large negative total water tendency ($-300$--$900 \text{ g m}^{-2} \text{ day}^{-1}$) is dominated by a loss of water vapor. Loss of cloud water has much less variability than water vapor, and contributes between $-100$ to $-500 \text{ g m}^{-2} \text{ day}^{-1}$ during each 15-min period. Positive ice tendencies counteract some of the general loss. While the height of the mixed-layer top remains steady over the 90-min analysis period, the mixed layer base moves downward at a rate of $50 \text{ m h}^{-1}$ (results not shown), possibly affecting the evolution of these layer integrals.

Water content tendencies are given by (4), where term $Q_{2s}$ represents diabatic moistening or microphysical processes (which include both phase transitions and sedimentation and is indicated by “MICROPHY” in the figures), and the last two terms represent horizontal and vertical advective tendencies, respectively. Since advective tendencies in the model are formulated in flux form, mean flow and eddy contributions to the advective tendency are calculated offline as:

$$\frac{\partial (w'q'_{s})}{\partial z} \approx \text{ADV}$$

where ADV is the total advective tendency calculated in the model, $\bar{u}, \bar{v}, \bar{w}, \bar{q}_{s}$ are 15-min averaged zonal wind, meridional wind, vertical wind, and water constituents, respectively, and $w'q'_{s}, v'q'_{s}, w'q'_{s}$ are resolved turbulent fluxes calculated from total flux and mean fields. $x_{c}, x_{w}, y_{v}, y_{s}$ are
Fig. 12. Time series of 15-min averaged water content tendencies from 20:00 Z–21:29 Z in upper entrainment zone (A) and mixed layer (B), in units of g m$^{-2}$ day$^{-1}$.

Fig. 13. (A) Processes that contribute to 15-min averaged total water content tendencies above the surface layer for the square box, in units of g m$^{-3}$ day$^{-1}$. Note that the net contribution due to microphysics for total water (MICROPHY) is equal to sedimentation, as condensational terms cancel. “ADV(flux)” is total flux estimated using Eq. (6). “ADV” is total advection output from the model. “TOTAL” is total water tendency. Entrainment zones indicated with gray shading. (B) Cloud liquid water and ice microphysical tendencies divided into contributions due to phase change and sedimentation, in units of g m$^{-3}$ day$^{-1}$. Cloud layer top and base indicated by red dashed lines.

Total water content tendencies above the base of the lower entrainment zone are plotted in Figs. 13 and 14. The net contribution of microphysical processes to the total water tendency is equal to sedimentation because phase-change terms cancel for total water. Since total, advective and microphysical tendency terms averaged over every time step were not available for analysis, Fig. 13a shows these tendency terms averaged over instantaneous fields output every minute. The ADV(flux) tendency term is the sum of...
Fig. 14. Processes that contribute to 15-min averaged water content tendencies above the surface layer for the square box, in units of g m\(^{-3}\) day\(^{-1}\). Note net contribution due to microphysics for total water in (A) is equal to sedimentation, as condensational terms cancel. The residual is equal to subgrid scale mixing plus diffusion. Mean advection terms (denoted with WM, UVM) are calculated by horizontally averaging tendencies. Horizontal eddy advection (UVP) is calculated as the divergence of fluxes across the domain. Vertical eddy advection (WP) is the divergence of the vertical eddy flux. Note change in scale in (A). Entrainment zones indicated with gray shading. (A) Total water. (B) Water vapor. (C) Cloud liquid water. (D) Cloud ice water. Cloud layer top and base indicated by red dashed lines.

the advective tendencies in Eq. (6), while ADV is the exact advective tendency output from the model. The difference between the ADV and ADV(flux) curves is an estimate of the error in the post-processed advective tendencies relative to tendencies output from the model, and is generally small throughout the profile.

At the top boundary of the upper entrainment zone there is a decrease in total water of \(-1\) g m\(^{-3}\) day\(^{-1}\) (Fig. 13a), with the dominant term being the vertical turbulent advection of water vapor (WP in Fig. 14a, b). Within the entrainment zone there is down gradient mixing of both water vapor and cloud liquid water such that turbulent vertical advection increases (decreases) cloud liquid water (water vapor) above 1.27 km and opposite below (Fig. 14b, c). Sedimentation, which is the microphysics term in Figs. 13a and 14a because phase transitions conserve total water, is a maximum within the upper entrainment zone due to the fallout of primarily liquid water and some ice into the top of the mixed layer. Thus, one significant process for moving water from the inversion into the mixed layer is liquid condensation in the entrainment zone (Fig. 14c) and its sedimentation (Fig. 13b). While ice sedimentation into the mixed layer is relatively large, most of this ice is actually mixed upward into the entrainment zone by turbulent eddies while little is actually formed there (Figs. 13b, 14d). At the lower boundary of the upper entrainment zone a positive (negative) tendency of water vapor (cloud liquid water) due to vertical turbulent fluxes is balanced closely by condensation/evaporation and sedimentation.

From 1.1 km to the top of the mixed layer, total water tendencies due to sedimentation and eddy vertical advection tend to cancel (Fig. 14a), such that the total mixed-layer tendency is a drying of approximately \(-2\) g m\(^{-3}\) day\(^{-1}\) that is essentially independent of height (Fig. 13a). Within the lower cloudy portion of the mixed layer, the largest tendency term is the increase (decrease) in water vapor (cloud liquid water) due to evaporation.

Figure 15a, b shows vertically resolved turbulent \((\overline{w q_v'})\) and mean \((\overline{w q_v})\) water fluxes, respectively. In Fig. 15b it is clearly seen that \(\overline{w q_v}\) is an order of magnitude larger than \(\overline{w q_v'}\). This is due to large vertical mass fluxes \((\overline{q_v}\delta w/\delta z)\) that do not contribute to vertical mean advective

\[\text{Height (km)}\]

\[\text{g/m}^3 \ast \text{m/s}\]

\[\text{g/m}^3 \ast \text{m/day}\]

\[\text{Fig. 15. Horizontally and temporally averaged vertical water content fluxes, in units of g m}^{-3} \text{ m s}^{-1}.\] Entrainment zones indicated with gray shading. (A) Eddy fluxes. (B) Mean fluxes. (C) Mean fluxes as in (B) except mean water vapor vertically averaged between 0.7–1.4 km is removed before calculating mean water vapor flux. (D) Vertical derivative of modified mean water vapor flux (WQv*) from (C) compared to water vapor tendency due to advection by mean vertical velocity (WM in Fig. 14b). Cloud layer top and base indicated by red dashed lines.
tendencies of water vapor \( \overline{\partial q_v/\partial z} \), WM in Fig. 14b). Figure 15b indicates that there is a mean larger-scale (larger than the 6.5 × 6.5 km square domain used in the analysis) circulation within the mixed layer and upper entrainment zone producing a horizontal mass flux into the entrainment zone and upper mixed layer, a downward mass flux within the mixed layer, and a horizontal mass flux out of the lower mixed layer. The largest vertical mean mass flux is located near the cloud base (~1 km), which suggests that this larger-scale circulation is driven by the cloud layer itself. In order to isolate the part of \( \overline{\partial q_v/\partial z} \) that contributes to \( \overline{\partial q_v/\partial z} \), the mean water vapor used to calculate \( \overline{\partial q_v/\partial z} \) in Fig. 15b is modified by subtracting its vertical average between 0.7–1.4 km, thereby using only the vertical perturbations of water vapor in the mean flux calculations. This modified mean water vapor flux better represents the smaller-scale contribution to the vertical water vapor mass flux \( \overline{\partial q_v/\partial z} \), and is much smaller in magnitude (Fig. 15c) than that found in Fig. 15b. Figure 15d shows the extent to which the mass flux contribution has been eliminated from the modified \( \overline{\partial q_v/\partial z} \) by comparing \( \overline{\partial q_v/\partial z} \) to \( \overline{\partial q_v/\partial z} \) from Fig. 15c. Differences between the two curves in Fig. 15d indicate that \( \overline{\partial q_v/\partial z} \) is overestimated near the top and bottom of the mixed layer.

Comparing Fig. 15a and c, it is seen that at the top of the upper entrainment zone both turbulent and mean vertical fluxes are essentially zero. Therefore, the decrease in total water by turbulent eddies in the upper part of the entrainment zone is primarily due to a downward transport of water vapor from below the top of the upper entrainment zone. In addition, the turbulent flux of total water at the mixed-layer top is positive, primarily due to positive fluxes of cloud liquid water and ice. The mean flux of total water is approximately equal to zero at the mixed-layer top, with a positive mean flux of vapor balancing a negative mean flux of cloud water (Fig. 15c). The slightly negative total water flux at the base of the mixed layer is primarily due to a negative flux of water vapor by the mean flow, which is partially offset by a small positive turbulent vapor flux. However, its magnitude is about ~0.0003 g m\(^{-2}\) s\(^{-1}\), which is an order of magnitude smaller than the vertical flux due to ice sedimentation at the mixed-layer base (results not shown). Thus, the net flux of water through the mixed-layer base is primarily due to sedimentation and not to mean or turbulent vertical motions.

### 5.4.5 Layer budgets

Following Curry et al. (1988), we calculate vertically integrated water content budgets in the mixed layer and upper entrainment zone with Eq. (4 and 6). Table 3 shows the contribution of advection and microphysics to water content tendencies in the upper entrainment zone. Note that the microphysics term (MICROPHY) in total water tendencies is equal to sedimentation. There is a net decrease in total water in the upper entrainment zone as sedimentation out is greater than net advection in. The entrainment zone loses ~99 g m\(^{-2}\) day\(^{-1}\) on average over the 90-min period, although this rate varies from ~30 to ~200 g m\(^{-2}\) day\(^{-1}\) for 15-min averages (Fig. 12). This net loss of total water is primarily due to a net cloud liquid water gain of 100 g m\(^{-2}\) day\(^{-1}\) offset by a water vapor loss of 203 g m\(^{-2}\) day\(^{-1}\). Because water vapor has no sedimentation, the 379 g m\(^{-2}\) day\(^{-1}\) of water vapor loss due to microphysics implies a liquid water gain of 379 g m\(^{-2}\) day\(^{-1}\) due to condensation, assuming minimal ice formation. The net \( q_c \) gain of 208 g m\(^{-2}\) day\(^{-1}\) from microphysics then implies cloud liquid water sedimentation of 30 g m\(^{-2}\) day\(^{-1}\) from the upper entrainment zone. Mean and eddy vertical advection produce a 100 g m\(^{-2}\) day\(^{-1}\) loss of \( q_c \), but a 181 g m\(^{-2}\) day\(^{-1}\) gain of water vapor. There is a relatively neutral ice tendency in this zone, as the 71 g m\(^{-2}\) day\(^{-1}\) gain due to lofting by eddy vertical advection from the mixed layer is offset by sedimentation. A small amount of cloud ice is produced through phase changes (deposition, freezing; Fig. 13b). Hence, the water budget in the entrainment zone consists of a net loss of total water primarily due to liquid water condensation and a loss of 72 % of this liquid water to the mixed layer through sedimentation and vertical advection. The vertical profiles (Fig. 14) additionally show that water vapor is primarily redistributed from the top of the entrainment zone to the base of the entrainment zone by vertical mixing due to resolved eddies.

Table 4 shows the contributions of advection and microphysics to water content tendencies integrated over the mixed layer from 0.82–1.24 km. The mixed layer loses ~696 g m\(^{-2}\) day\(^{-1}\) of water averaged over the 90-min period. The rate of total water depletion from the mixed layer varies from ~300 to ~950 g m\(^{-2}\) day\(^{-1}\) over the 15-min periods, while liquid water loss is ~281 g m\(^{-2}\) day\(^{-1}\) and ranges from ~100 to ~450 g m\(^{-2}\) day\(^{-1}\). The mixed layer is 7X deeper than the upper entrainment zone and loses 7X as much total water, with 43 % of this loss due to horizontal advection. Mean vertical advection, sedimentation, and upward transport by eddies each contribute between 15 % and 21 % of this loss. In the cloudy portion of the mixed layer, evaporation and collection reduces the cloud liquid water at a rate of ~523 g m\(^{-2}\) day\(^{-1}\), while ice and water vapor both increase through these processes (Fig. 13b). A substantial amount of the water vapor increase is converted to cloud ice through deposition (i.e., the Bergeron process). There is also a substantial loss (~136 g m\(^{-2}\) day\(^{-1}\)) of cloud liquid water due to mean horizontal advection and loss of water vapor due to mean vertical advection (Fig. 14b). Within the cloud in the mixed layer, sedimentation produces decreases of ice and smaller increases in liquid water (Fig. 13b). Below cloud base within the mixed layer, ice amounts increase weakly due to both sedimentation and vapor deposition, while weak losses of water vapor occur from all terms, including mean horizontal advection (Fig. 14b).

Considering total water alone, the cloud should eventually dissipate due to net loss of water in both the upper
Table 3. Mean (± one standard deviation) contribution of advection and microphysics to time and horizontally averaged water content tendencies in the upper entrainment zone, in units of g m$^{-2}$ day$^{-1}$. Advection by the mean flow is calculated from 15-min averaged fields. Eddies are defined as deviations from the 15-min averages. Total* is the sum of advection terms plus microphysics and is not exactly equal to total tendency due to errors incurred by calculating the advection terms offline (see discussion of Fig. 13).

<table>
<thead>
<tr>
<th>Component</th>
<th>UVM</th>
<th>UVP</th>
<th>WM</th>
<th>WP</th>
<th>MICROPHY</th>
<th>Total*</th>
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<td>$-6 \pm 3$</td>
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<td>$-0 \pm 1$</td>
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<td>$-62 \pm 13$</td>
<td>$5 \pm 3$</td>
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Table 4. The same as Table 3 except for the mixed layer budget.

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<th>Component</th>
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<th>UVP</th>
<th>WM</th>
<th>WP</th>
<th>MICROPHY</th>
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<td>$156 \pm 23$</td>
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</tbody>
</table>

entainment zone and mixed layer. Transport of water vapor into the lower part of the upper entrainment zone is large enough to cause continual liquid condensation that is transported or sedimented downward into the mixed layer. In the mixed layer, loss due to microphysics exceeds this injection of cloud liquid water from the entrainment zone, resulting in a continual net loss of cloud liquid water.

5.5 Dowladraft and updraft averages

Vapor, liquid, and ice water tendencies averaged over in-cloud updrafts and downdrafts separately in the square domain and temporally averaged over the 90-min period are plotted in Fig. 16. Also shown in Fig. 16 are mean vertical velocity and $\theta_e$ profiles averaged over downdrafts and updrafts separately. Downdrafts are defined as gridpoints where minimum vertical velocity within the cloud layer is less than $-30$ cm s$^{-1}$ (see Fig. 16c). Updrafts are defined as gridpoints where maximum vertical velocity within the cloud layer is greater than 20 cm s$^{-1}$ (see Fig. 16d). Out of 16 900 gridpoints, approximately 3000–4000 gridpoints at a given time are classified as downdrafts and 4000–5000 gridpoints are classified as updrafts. These numbers are consistent with cloud dynamics forced by radiative cooling at cloud top, which result in narrower yet stronger downdrafts relative to updrafts. Vertical velocity above the cloud layer is approximately $-0.4$ cm s$^{-1}$ in averages over updrafts and downdrafts (Fig. 11b). Figure 16a and b show the contributions of cloud water, cloud ice, and water vapor to downdraft and updraft total water tendencies, respectively. It is clearly seen that within the upper entrainment zone, the decrease in water vapor and increase in cloud liquid water seen in the total main averages (Fig. 11) only occur above downdrafts. Above updrafts, the opposite, yet somewhat weaker, tendencies are present. In downdrafts, mixed-layer cloud water decreases while water vapor, ice, and total water increase. Compensating effects occur in updrafts, where mixed-layer cloud liquid water increases (within the cloud) while a decrease of water vapor, ice, and total water occurs throughout. Note that the base of cloud liquid water increases in the updrafts occurs above the base of cloud liquid water decreases in the downdrafts, suggesting a modulation of cloud base height by vertical motions.

Tendencies in water vapor and cloud liquid water in updrafts and downdrafts are due to compensating large microphysics and advection tendencies that sum to a smaller residual (see Fig. 17). Within the cloud layer, in downdrafts, opposite vertical gradients of cloud liquid water and water vapor cause an increase in cloud liquid water and decrease in water vapor by vertical advection, with the cloud liquid water then decreasing by evaporating and thereby increasing water vapor. In this process the microphysical tendencies are slightly dominant, resulting in small residuals of opposite sign for liquid and vapor (Fig. 17a, c). Approximately the opposite is true in updrafts, although advective and microphysical tendency magnitudes are smaller and more nearly balanced leading to smaller total tendencies of opposite signs relative to downdrafts (Fig. 17 b, d). Ice tendencies are dominated by advective tendencies in both updrafts and downdrafts, while sedimentation and total microphysics terms are quite small (Fig. 17 e, f).

It is important to note that condensation occurs in the upper entrainment zone in both updrafts and downdrafts (Fig. 17a, b, c, d). This process of “radiative encroachment,”
Fig. 16. Average profiles in downdrafts (left side; A, C) and updrafts (right side; B, D) in the square box of liquid, vapor, ice and total water mixing ratio tendencies (A, B: g kg$^{-1}$ day$^{-1}$) and mean resolved vertical velocity (blue, ± one standard deviation of one-min averages dashed; cm s$^{-1}$) and equivalent potential temperature (black; K) (C, D). Entrainment zones indicated with gray shading. Cloud layer top and base indicated by red dashed lines in (A, B).

or forcing of direct condensation by cooling that cannot be balanced by convection, is a process that contributes to the positive cloud water tendency in the upper entrainment zone (Fig. 11). This process occurs because of the specific humidity inversion that is coincident with the temperature inversion. We also emphasize that this radiative condensational processes, occurring above both updrafts and downdrafts, is quite different from the adiabatic cooling process simultaneously producing condensation in the mixed-layer updrafts as seen in Fig. 17b. Lastly, while cloud liquid condensation and evaporation occur in mixed-layer updrafts and downdrafts, respectively, deposition on cloud ice occurs in both updrafts and downdrafts (i.e., the difference between sedimentation and microphysics terms in Fig. 17 e, f). Slightly more ice deposition occurs in updrafts.

6 Summary and discussion

In this paper we use high-resolution nested LES simulations to quantify the processes involved in the maintenance and persistence of a single-layer, decoupled AMPS that was observed near Barrow, Alaska, during ISDAC on 8 April 2008.
Longwave radiative cooling peaks within the temperature inversion and upper entrainment zone but also extends 80 m down into the mixed layer, coincident with turbulent vertical potential temperature fluxes. The average potential temperature tendency due to longwave cooling at the mixed-layer top is approximately $-80 \text{ K day}^{-1}$. There is a relatively uniform net cooling of $-4 \text{ K day}^{-1}$ within the mixed layer.

Buoyancy, shear, pressure transport, and TKE transport make significant contributions to the vertical distribution of TKE tendencies. In the upper entrainment zone, TKE production is dominated by pressure transport and shear but limited by buoyancy. At the top of the mixed layer shear is the dominant production term. Moving down into the mixed layer, shear remains important along with buoyancy production. TKE is advected downward to the base of the mixed layer where TKE production by other terms is small. All production terms become small below the mixed layer, effectively decoupling the cloud from the lower troposphere and surface.

At the top boundary of the upper entrainment zone there is a decrease in total water of $-1 \text{ g m}^{-3} \text{ day}^{-1}$ primarily due to eddy vertical advection of water vapor. Within the entrainment zone there is down gradient mixing by turbulent eddies that causes an upward (downward) transport of cloud liquid water (water vapor) above the liquid water maximum at the base of the upper entrainment zone (top of the mixed layer), and oppositely below. In terms of total water, entrainment moistens the cloud layer in the lower part of the upper entrainment zone (Fig. 14b). The increase (decrease) in water vapor (cloud liquid water) due to turbulent fluxes in the lower part of the entrainment zone is closely balanced by a decrease (increase) by condensation and liquid sedimentation, with sedimentation exceeding advection of total water by $2 \text{ g m}^{-3} \text{ day}^{-1}$ at the lower boundary. The upper entrainment zone loses an average of $-99 \text{ g m}^{-2} \text{ day}^{-1}$ of total water to the mixed layer.

The mixed layer loses total water at a rate of $-696 \text{ g m}^{-2} \text{ day}^{-1}$. This tendency is primarily due to horizontal advection by the mean flow, while $-387 \text{ g m}^{-2} \text{ day}^{-1}$ of total water loss is approximately equally divided between losses due to turbulent vertical fluxes, mean vertical advection, and sedimentation (Table 4). Neglecting tendencies due to mean horizontal wind, net loss of cloud liquid water is due to microphysical processes that are partially offset by mean vertical advection at the mixed-layer top. Turbulent and mean fluxes of total water at the mixed-layer top are positive and larger than fluxes at the base.

The average loss of cloud water from the upper entrainment zone plus mixed-layer system is $-181 \text{ g m}^{-2} \text{ day}^{-1}$, or 7.5 g m$^{-2}$ h$^{-1}$. However, over this 90-min period the upper entrainment zone gains cloud liquid water while continually losing total water. This is due to the continuous source of water vapor provided to the cloud layer by turbulent down gradient mixing and condensation forced by radiative cooling that cannot be balanced by convection. For an initial liquid water path of 50 g m$^{-2}$, assuming no change in the dynamical balance, a cloud could persist at this rate for 6.7 h. The net loss of cloud water is only 23% of the loss of total water, i.e. the mixed layer plus entrainment zone is losing vapor 3.5 times faster than it is losing cloud liquid water.

Interestingly, mean subsidence above the upper entrainment zone is of the same order as mean subsidence in subtropical cloud-topped boundary layers (see Wood and Bretherton, 2004) and other LES simulations of AMPS (see Klein et al., 2009). However, mean subsidence goes to zero at the upper entrainment zone top, resulting in no net vertical flux of water into the upper entrainment zone. Essentially all vertical transport of water into the mixed layer initiates in the upper entrainment zone.

This study has shown that sedimentation plays a dominant role in vertical transport and depletion of water from a decoupled AMPS cloud system. This sedimentation is due to both gravitational settling of liquid water in the mixed layer and continuous precipitation of ice out of the mixed layer. In this model study, ice mass production might be underestimated relative to retrievals and aircraft observations (although there is uncertainty to these comparisons). It is unclear what impact greater ice production would have on the simulation. For example, in subtropical boundary layers, sedimentation removes water near cloud top resulting in less entrainment of dry, warm air and a more persistent cloud (Ackerman et al., 2004; Bretherton et al., 2007). Sedimentation in AMPS at cloud top may have the opposite effect, as entrainment acts to further moisten the cloud. Also, production of more ice would cause more condensational heating to balance longwave cooling and thereby modify vertical motions in the mixed layer. In addition, more ice production may cause more moistening of the surface layer.

In both updrafts and downdrafts, vertical velocity above the cloud layer is approximately $-0.4 \text{ cm s}^{-1}$. The decrease in water vapor and increase in cloud liquid water in the upper entrainment zone occurs primarily above mixed-layer downdrafts. Above mixed-layer updrafts, the opposite occurs. Similar opposing tendencies among the water phases in updrafts and downdrafts are seen in the mixed layer. Of primary importance is that condensation occurs within the upper entrainment zone above both updrafts and downdrafts due to diabatic radiative cooling, while condensation within the mixed layer occurs only in updrafts due to adiabatic cooling.

Results of this nested LES study form a relatively simple conceptual model of decoupled AMPS where the essential structures and processes are:

1. A humidity inversion at cloud top provides a weak source of moisture to the cloud layer via entrainment caused by cloud-generated turbulence. This continual downward transport of water vapor into the cloud layer supports its persistence and represents a positive feedback.
2. The primary and necessary source of energy for the system is longwave radiative cooling at, and near, cloud top. Radiative cooling does at least two things: (1) Forces direct condensation in non-buoyant parcels near cloud top that are inside the temperature and moisture inversions; (2) Forces turbulence and buoyancy-driven overturning of parcels within a cloudy mixed layer, with additional condensation occurring in updrafts.

3. Cloud ice depositional growth occurs primarily in the mixed layer in both updrafts and downdrafts, although slightly more in the latter.

4. The primary transport of total water from the entrainment zone into the mixed layer is via sedimentation of liquid water. Ice precipitation is the primary net sink of condensed mass from the cloudy mixed layer.

We speculate that collapse of the system occurs when the moisture source above the cloud is exhausted (i.e., supply rate of moisture due to entrainment is less than the sedimentation rate of condensate out of the cloud mixed layer for a long enough time) and/or condensed liquid water drops below its threshold for efficient emission causing radiative cooling, and therefore buoyant overturning, to diminish (see Morrison et al., 2011 for a discussion on this point).

We acknowledge that, while consistent with many observations and past studies, the budgets and processes described here are primarily based on the model representation of this one AMPS case. Hence, model configuration and physics may have significant impacts on the results. A deficiency in our simulations (and in many AMPS simulations) is the apparent underestimation of cloud ice. Future observational and modeling work should obtain detailed observations to verify the processes described here, especially those within the upper entrainment zone and the upper portion of the mixed layer, improve model representations, explore the generality of these results, and attempt to understand the processes modulating the coupling of AMPS with surface forcing.

Supplementary material related to this article is available online at: http://www.atmos-chem-phys.net/11/10127-2011/aep-11-10127-2011-supplement.pdf.

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